

# MATH 221, Spring 2018 - Homework 7 Solutions

Due Tuesday, April 3

## Section 4.3

Page 213, Problem 3:

The matrix whose columns are the given set of vectors is  $\begin{bmatrix} 1 & 3 & -2 \\ 0 & 1 & -1 \\ -3 & -4 & 1 \end{bmatrix}$ , which reduces to  $\begin{bmatrix} 1 & 3 & -2 \\ 0 & 1 & -1 \\ 0 & 5 & -5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 3 & -2 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$ .

Because there are only two pivot positions, **the set of vectors are neither linearly independent nor span  $\mathbb{R}^3$** , thus **the set of vectors do NOT form a basis of  $\mathbb{R}^3$** .

Page 213, Problem 8:

The matrix whose columns are the given set of vectors is  $\begin{bmatrix} 1 & 0 & 2 & 0 \\ -2 & 3 & -1 & 0 \\ 3 & -1 & 5 & -1 \end{bmatrix}$ . Because there are four columns, **the**

**set cannot be linearly independent in  $\mathbb{R}^3$** . Thus, **the set of vectors do NOT form a basis of  $\mathbb{R}^3$** .

To determine if the set of vectors span  $\mathbb{R}^3$ , row-reduce the matrix:

$$\begin{bmatrix} 1 & 0 & 2 & 0 \\ -2 & 3 & -1 & 0 \\ 3 & -1 & 5 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 3 & 3 & 0 \\ 0 & -1 & -1 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

Because there is a pivot position in each row, **the set of vectors do span  $\mathbb{R}^3$** .

Page 213, Problem 13:

To find a basis for ColA, use Theorem 6 of this section. Notice that the pivot positions are in columns 1 and 2 (look at matrix  $B$ , which is in row echelon form). Use these columns from matrix  $A$  to form a basis. Therefore, a basis for ColA

is  $\left\{ \begin{bmatrix} -2 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} 4 \\ -6 \\ 8 \end{bmatrix} \right\}$ . To find a basis for NulA, write the general solution to  $A\mathbf{x} = \mathbf{0}$  in terms of the free variables

$$(x_3 \text{ and } x_4): \mathbf{x} = x_3 \begin{bmatrix} -6 \\ -5/2 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -5 \\ -3/2 \\ 0 \\ 1 \end{bmatrix}. \text{ Thus a basis for NulA is } \left\{ \begin{bmatrix} -6 \\ -5/2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -5 \\ -3/2 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

Page 214, Problem 14:

To find a basis for  $\text{Col}A$ , use Theorem 6 of this section. Notice that the pivot positions are in columns 1, 3, and 5 (look at matrix  $B$ , which is in row echelon form). Use these columns from matrix  $A$  to form a basis. Therefore, a basis for

$\text{Col}A$  is  $\left\{ \begin{bmatrix} 1 \\ 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \\ -3 \\ 0 \end{bmatrix}, \begin{bmatrix} 8 \\ 8 \\ 9 \\ 9 \end{bmatrix} \right\}$ . To find a basis for  $\text{Nul}A$ , we need the general solution to  $A\mathbf{x} = \mathbf{0}$  in terms of the

free variables ( $x_2$  and  $x_4$ ). Because matrix  $B$  is only in row echelon form, reduce it to reduced row echelon form:

$$\begin{bmatrix} 1 & 2 & 0 & 2 & 5 \\ 0 & 0 & 3 & -6 & 3 \\ 0 & 0 & 0 & 0 & -7 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 0 & 2 & 0 \\ 0 & 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \cdot \mathbf{x} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -2 \\ 0 \\ 2 \\ 1 \\ 0 \end{bmatrix}. \text{ Thus a basis for } \text{Nul}A \text{ is } \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ 2 \\ 1 \\ 0 \end{bmatrix} \right\}.$$

Page 214, Problem 21b:

True or False: If  $H = \text{Span}\{\mathbf{b}_1, \dots, \mathbf{b}_p\}$ , then  $\{\mathbf{b}_1, \dots, \mathbf{b}_p\}$  is a basis for  $H$ .

**FALSE:** The set  $\{\mathbf{b}_1, \dots, \mathbf{b}_p\}$  must also be linearly independent.

Page 214, Problem 21c:

True or False: The columns of an invertible  $n \times n$  matrix form a basis for  $\mathbb{R}^n$ .

**TRUE:** Because the matrix is invertible, the columns span  $\mathbb{R}^n$  and are linearly independent (by the Invertible Matrix Theorem). Hence, the columns form a basis for  $\mathbb{R}^n$ .

Page 214, Problem 21d:

True or False: A basis is a spanning set that is as large as possible.

**FALSE:** A basis is a spanning set that is as small possible (read “Two Views of a Basis” on p. 212).

Page 214, Problem 22a:

True or False: A linearly independent set in a subspace  $H$  is a basis for  $H$ .

**FALSE:** In order to be a basis, the set must also span  $H$  (by definition).

Page 214, Problem 22b:

True or False: If a finite set  $S$  of nonzero vectors spans a vector space  $V$ , then some subset of  $S$  is a basis for  $V$ .

**TRUE:** By the Spanning Set Theorem, removing linearly dependent vectors in  $S$  will still result in a spanning set (this new set is a subset of  $S$ ). Because the new set will eventually only contain linearly independent vectors, the set will be a basis for  $V$ .

Page 213, Problem 22e:

True or False: If  $B$  is an echelon form of a matrix  $A$ , then the pivot columns of  $B$  form a basis for  $\text{Col}A$ .

**FALSE:** The pivot columns in  $B$  tell which columns in matrix  $A$  form the basis for  $\text{Col}A$  (see the warning after Theorem 6 on page 212).

Page 214, Problem 25:

While it might seem that  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  is a spanning set for  $H$ , it is not. Notice that  $H$  is a subset of  $\text{Span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ .

Also, there are vectors in  $\text{Span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  which are not in  $H$ , such as  $\mathbf{v}_1$  and  $\mathbf{v}_3$  (the second and third elements of these vectors are not equal). Therefore,  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  does not span  $H$ , so  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  cannot be a basis for  $H$ .

Page 215, Problem 30:

Since  $k > n$ , there exist more vectors than there are entries in each vector, so the set is linearly dependent by Theorem 8.

Since the set is not linearly independent, it cannot be a basis for  $\mathbb{R}^n$ .