MATH221 quiz #3, 12/03/19 Solutions Total 100

By enrolling in this course, each student assumes the responsibilities of an active participant in UMBC's scholarly community in which everyone's academic work and behavior are held to the highest standards of honesty. Cheating, fabrication, plagiarism, and helping others to commit these acts are all forms of academic dishonesty, and they are wrong. Academic misconduct could result in disciplinary action that may include, but is not limited to, suspension or dismissal.

Show all work legibly.

Name:_____

1. (20) Let
$$A = \begin{bmatrix} 1 & 2 & 4 \\ 1 & 3 & 9 \\ 1 & 4 & 16 \end{bmatrix}$$
. Compute det A

Solution.

$$\det A = \det \begin{bmatrix} 1 & 2 & 4 \\ 0 & 1 & 5 \\ 0 & 2 & 12 \end{bmatrix} = \det \begin{bmatrix} 1 & 2 & 4 \\ 0 & 1 & 5 \\ 0 & 0 & 2 \end{bmatrix} = 2.$$

 $\det A =$

2. (40) Let
$$A = \begin{bmatrix} 2 & -2 & -2 \\ 3 & -3 & -2 \\ 2 & -2 & -2 \end{bmatrix}$$
 with the eigenvalues $\lambda_1 = 0, \lambda_2 = -1, \lambda_3 = -2$.

(a) (20) Find eigenvectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 corresponding to the eigenvalues λ_1 , λ_2 , and λ_3 .

Solution. A solution for
$$(A - \lambda_1)\mathbf{x} = 0$$
 is $\mathbf{v}_1 = \begin{bmatrix} 1\\1\\0 \end{bmatrix}$.
A solution for $(A - \lambda_2)\mathbf{x} = 0$ is $\mathbf{v}_1 = \begin{bmatrix} 2\\1\\2 \end{bmatrix}$.
A solution for $(A - \lambda_3)\mathbf{x} = 0$ is $\mathbf{v}_1 = \begin{bmatrix} 1\\1\\1 \end{bmatrix}$.
 $\mathbf{v}_1 = \mathbf{v}_2 = \mathbf{v}_3 = \mathbf{v}_3 = \mathbf{v}_3$

(b) (10) Let
$$V = \begin{bmatrix} -1 & 2 & 1 \\ 1 & 1 & 1 \\ 0 & 2 & 1 \end{bmatrix}$$
. Find V^{-1} if exists.

Solution.

$$\begin{bmatrix} -1 & 2 & 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 & 1 & 0 \\ 0 & 2 & 1 & 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & -1 & -1 & 0 & 0 \\ 0 & 3 & 2 & 1 & 1 & 0 \\ 0 & 2 & 1 & 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & -1 & -1 & 0 & 0 \\ 0 & 2 & 1 & 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & -1 & -1 & 0 & 0 \\ 0 & 1 & 2/3 & 1/3 & 1/3 & 0 \\ 0 & 0 & -1/3 & -2/3 & -2/3 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & -1 & -1 & 0 & 0 \\ 0 & 1 & 2/3 & 1/3 & 1/3 & 0 \\ 0 & 0 & 1 & 2 & 2 & -3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & -1 & -1 & 0 & 0 \\ 0 & 1 & 2/3 & 1/3 & 1/3 & 0 \\ 0 & 0 & 1 & 2 & 2 & -3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & -1 & 0 & 1 \\ 0 & 1 & 0 & -1 & -1 & 2 \\ 0 & 0 & 1 & 2 & 2 & -3 \end{bmatrix}$$

 $V^{-1} =$

(c) (10) Compute A^{10} .

Solution. $A^{10} = VD^{10}V^{-1}$, where

$$D = \begin{bmatrix} 0 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -2 \end{bmatrix}, V = \begin{bmatrix} 1 & 2 & 1 \\ 1 & 1 & 1 \\ 0 & 2 & 1 \end{bmatrix} \text{ and } V^{-1} = \begin{bmatrix} 1 & 0 & -1 \\ 1 & -1 & 0 \\ -2 & 2 & 1 \end{bmatrix}$$
$$A^{10} =$$

3. (20) Let V be a subspace of \mathbf{R}^3 with an orthonormal basis $\{\mathbf{v}_1, \mathbf{v}_2\}$, and \mathbf{w} is a vector of norm 1 in V^{\perp} . True or False? The set $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{w}\}$ is a basis for \mathbf{R}^3 .

Solution. Let $c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c\mathbf{w} = 0$. Dot multiplication of the left hand side and the right hand side with \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{w} yields $c_1 = c_2 = c = 0$. This shows that the set $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{w}\}$ is linearly independent, hence a basis for \mathbf{R}^3 .

Mark one and explain.

• True • False

4. (20) Let $V = \text{span} \{\mathbf{v}_1, \mathbf{v}_2\}$ where $\mathbf{v}_1 = \begin{bmatrix} 0\\1\\2 \end{bmatrix}$ and $\mathbf{v}_2 = \begin{bmatrix} 3\\4\\5 \end{bmatrix}$. For $\mathbf{w} = \begin{bmatrix} 1\\1\\1 \end{bmatrix}$ find the orthogonal projection of \mathbf{w} onto V.

Solution. Since \mathbf{w} is in V the orthogonal projection is \mathbf{w} . the orthogonal projection is

5. (20) Use the basis $\{\mathbf{v}_1, \mathbf{v}_2\}$ for \mathbf{R}^2 with $\mathbf{v}_1 = \begin{bmatrix} 1\\1 \end{bmatrix}$ and $\mathbf{v}_2 = \begin{bmatrix} -1\\1 \end{bmatrix}$ to build an orthonormal basis $\{\mathbf{u}_1, \mathbf{u}_2\}$ for \mathbf{R}^2 .

Solution. Since $\mathbf{v}_1^T \mathbf{v}_2 = 0$ a simple possible choice of an orthonormal basis is $\mathbf{u}_1 = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$ and $\mathbf{u}_2 = \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$. $\mathbf{u}_1 = \mathbf{u}_2 =$